

# Set-Valued Retractions and Subdivision Algorithms for Approximating Feasible Sets

Robert Baier<sup>1</sup> and Tomáš Roubal<sup>2</sup>

<sup>1</sup>Department of Mathematics, University of Bayreuth, Germany

<sup>2</sup>UTIA, Czech Academy of Sciences, Prague, Czech Republic

## Abstract

A classical retraction appearing in topology is a continuous function  $r : X \rightarrow Y$  mapping  $X$  to a subset  $Y$  of  $X$  such that the idempotency condition  $r(y) = y$  holds for all elements  $y \in Y$ . Since  $Y$  can be implicitly defined via complicated constraints or properties in applications, the computation of its range  $Y$  is of general interest.

In [3] we study upper semi-continuous set-valued retractions  $R : X \rightrightarrows Y$  with nonempty closed values and adapt a subdivision algorithm for reachable sets of differential inclusions in [2] to the computation of ranges. The metric projection computed by a nonlinear optimizer and the selection step of a subdivision method approximating the reachable sets are generalized to ranges of set-valued retractions.

For set-valued retractions we focus on the (weaker) invariance condition  $y \in R(y)$  for all elements  $y$  in  $Y$  and not on the stronger condition  $R(y) = \{y\}$ . This condition fits better to a best approximation  $y$  of a given point  $x$  in  $Y$  and to fixed points  $\hat{x} \in F(\hat{x})$  for a set-valued map  $F : X \rightrightarrows Y$ . The subdivision algorithm which was originally introduced in [1] starts from a bounding box  $G$ , uses a refinement step of the box collection in level  $k$  and decides in a selection step which refined boxes approximate the invariant or attractor set. In the selection process for ranges we check the intersection of the image of a refined box  $B$  for  $R$  with  $B$  via computing best approximations of test points in  $G$ . If nonempty, this classifies the case that the box has a nonempty intersection with the range of  $R$ .

Example classes of this family are the set-valued projection of compact sets, feasible sets of optimization problems, window retractions, special marginal maps, and the projection to the set of fixed points. A convergence result for the subdivision method shows that the union of all boxes from the box collection for increasing refinement level yields the range of a set-valued retraction.

Special examples show that set-valued retractions are more general than set-valued projections and can exist, if there are no existing continuous (single-valued) retractions so that the approximation of their ranges (if given implicitly via constraints or properties) are a challenging field of set-valued analysis.

## References:

- [1] M. Dellnitz and A. Hohmann: A subdivision algorithm for the computation of unstable manifolds and global attractors. *Numer. Math.* 75 (1997), 293-317.
- [2] W. Riedl, R. Baier, and M. Gerdt: Optimization-based subdivision algorithm for reachable sets. *J. Comput. Dyn.* 8 (2021), 99-130.
- [3] R. Baier, and T. Roubal: Set-Valued Retractions and Subdivision Algorithms for Feasible Set Approximation. Bayreuth–Prague, forthcoming in July 2026.